

Wave Propagation Characteristics of a Reactively Loaded Microstrip

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Abstract — The characteristics of wave propagation along a reactively loaded microstrip operating in its first higher-order mode are investigated by means of the transverse-resonance and two-dimensional finite-difference time-domain techniques. It is found that the phase velocity along the microstrip and the cutoff frequency of its first higher-order mode are functions of the reactive-load value. These effects are used to design fixed-frequency continuously beam-steerable leaky-wave antennas, and antennas with a continuously adjustable operating frequency range.

I. INTRODUCTION

The leakage mechanism of a microstrip operating in its first higher-order mode (EH_1) has been used successfully in the design of microstrip leaky-wave antennas [1,2]. Recently, applications employing this microstrip as a radiating element have appeared in the literature, and have dealt with fixed-frequency continuous main-beam steering [3,4], dual-beam frequency scanning [5], and phased arrays with a reconfigurable aperture [6].

In [3,4], the leaky-wave microstrip was divided into a number of regular sections along the direction of wave propagation. Identical varactor diodes were used to connect adjacent sections, so as to form a finite-length periodic structure. By reverse-biasing the series-connected varactor diodes between 0 and -900 volts, a 60-degree scan range was achieved at 5.2 GHz both theoretically and experimentally.

Interest in reducing the DC-voltage requirement of the fixed-frequency continuously beam-steerable periodic microstrip introduced in [3,4] without resorting to varactors mounted in shunt through the dielectric, prompted the author to investigate the propagation characteristics of waves traveling along a new structure, the reactively loaded microstrip. The theoretical details of this investigation will be presented in the sections that follow, and will focus on the first higher-order mode of operation.

II. ANALYSIS

A. Propagation-Constant Calculations

A cross-sectional view of the microstrip under investigation is shown in Fig. 1(a). A reactive sheet of

width $\delta \ll h$, and surface reactance $X_s = -1/(\omega C)$ (Ω/square) lies along the bisecting line of the top $2d$ -wide conductor. Here, the dielectric thickness h is chosen such that surface-wave modes beyond the TM_0 mode are cutoff.

The structure shown in Fig. 1(a) supports hybrid modes whose complex propagation constants may be found by application of the transverse-resonance technique [2,7,8]. An essential ingredient to the success of this technique is an accurate prediction of Z_h , the impedance of the open end located at $x = \pm d$.

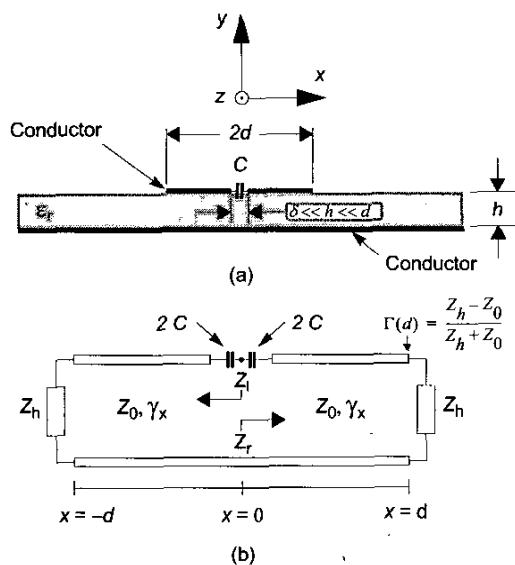


Fig. 1. A reactively loaded microstrip. (a) Cross-sectional view. (b) A transmission-line model for wave propagation along the x direction.

In [2], a Wiener-Hopf technique was used to find the impedance of the open end [9], which resulted in an accurate prediction of the propagation constants of the modes supported by an unloaded microstrip. Here, the open-end impedance is found by making use of the two-dimensional finite-difference time-domain (2D FDTD) technique [10], in which use is made of a twelve-cell-thick perfectly matched layer (PML) [11] on the top, left, and

right walls as shown in Fig. 2. A y -polarized Gaussian pulse generated by a voltage source located between the conducting bottom wall and the top strip at $x=x_g$ is incident on the open end. The ratio of the Fourier transforms of the y -polarized electric field and z -polarized magnetic field at the open end ($x=x_h$) provides Z_h .

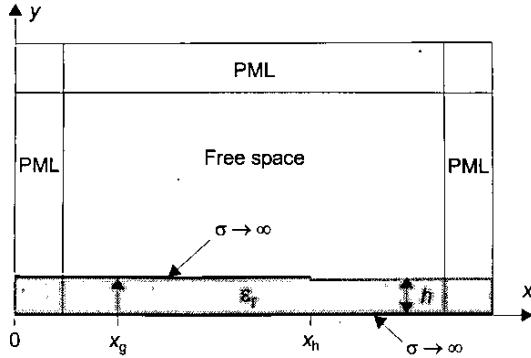


Fig. 2. 2D-FDTD setup for calculating the impedance of the open end located at $x = x_h$.

The stage is now set for applying the transverse-resonance technique [2,7,8] to the circuit shown in Fig. 1(b). This results in the following equation for the complex propagation constant along the x direction:

$$\gamma_x = \frac{j}{2d} \left(\ln \left| \frac{-jX_s/2 + Z_0}{-jX_s/2 - Z_0} \right| - \ln |\Gamma(d)| + j(\tau - \phi + 2n\pi) \right) \quad (1)$$

$$n = 0, 1, 2, \dots$$

where n is the propagation-mode index, Γ is the reflection coefficient, Z_0 is the TEM wave impedance in a dielectric having a relative constant ϵ_r , $\phi = \text{Arg}(\Gamma(d))$, and

$$\tau = \text{Arg} \left(\frac{-jX_s/2 + Z_0}{-jX_s/2 - Z_0} \right)$$

With γ_x known, the complex propagation constant γ_z along the direction of wave propagation may be calculated readily using

$$\gamma_z = \sqrt{k_s^2 - \gamma_x^2}, \quad (2)$$

where k_s is the propagation constant of the TM_0 surface-wave mode, assumed by a proper choice of h to be the only propagating one. Eqs. (1) and (2) show the dependence of γ_z on the surface reactance X_s , and thus on the reactive loading. The extent of this dependence and its implications will be explored next by means of two antenna examples.

B. Dependence of γ_z on the Value of the Reactive Load

The analysis technique described in Section A was used to calculate the normalized leakage and propagation constants of the EH_1 mode propagating along a reactively loaded microstrip. The results are shown in Figs. 3 and 4 for different values of $C \in [0.05, 1.0] \text{ pF}$. Here, the microstrip dielectric constant $\epsilon_r = 2.2$, the dielectric thickness $h = 0.127 \text{ mm}$, and the strip width $2d = 3.5 \text{ mm}$.

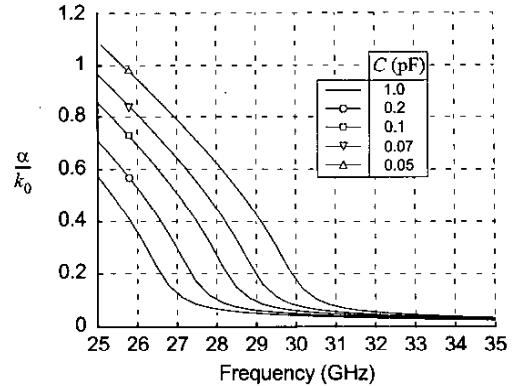


Fig. 3. The normalized leakage constant α/k_0 of the EH_1 mode in a reactively loaded microstrip with $\epsilon_r = 2.2$, $h = 0.127 \text{ mm}$, $2d = 3.5 \text{ mm}$, and $C \in [0.05, 1.0] \text{ pF}$. The free-space wave number is denoted by k_0 .

Figure 4 shows that an increasing value of C has the effect of making the microstrip waveguide appear wider, and causes a downward shift in the cutoff frequency of the EH_1 mode. Here, a shift of about 3 GHz in the cutoff frequency of the EH_1 mode is observed as C is increased from 0.05 to 1 pF. Figure 4 also shows that at a constant frequency f , a continuous increase in the value of C is accompanied by a continuous decrease in the phase velocity along the microstrip, and thus a continuous movement of the main-beam maximum toward endfire.

For a microstrip of length L , the H-plane power-gain pattern may be calculated by treating the microstrip as a line source [12], and by making use of the element factor of an x -directed infinitesimal current element lying on a grounded dielectric slab of infinite extent [13]. For a microstrip of length $L = 4.9 \lambda_0$, where λ_0 is the free-space wavelength at $f = 30 \text{ GHz}$, this approach results in the normalized H-plane power-gain patterns shown in Fig. 5 for different values of $C \in [0.05, 1.0] \text{ pF}$. This choice of L ensures that at least 90% of the input power is radiated by the time the EH_1 wave reaches the end of the microstrip.

Figure 5 shows that as C is decreased from 1 to 0.05 pF, the main-beam maximum scans a 35° range at a constant frequency $f=30$ GHz. This is accompanied by a widening of the main beam, and is due mainly to the fact that the leakage constant α shown in Fig. 3 increases as C is decreased, resulting in a shorter radiating aperture.

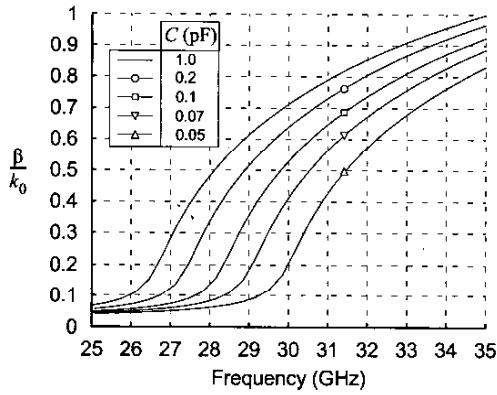


Fig. 4. The normalized phase constant β/k_0 of the EH_1 mode in a reactively loaded microstrip with $\epsilon_r = 2.2$, $h = 0.127$ mm, $2d = 3.5$ mm, and $C \in [0.05, 1.0]$ pF.

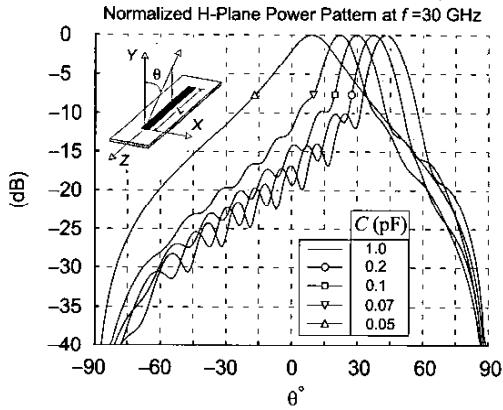


Fig. 5. The normalized H -plane power-gain patterns of the $4.9\lambda_0$ -long reactively loaded microstrip for $\epsilon_r = 2.2$, $f = 30$ GHz, and $C \in [0.05, 1.0]$ pF. The normalization factor for each of the patterns is its maximum power gain.

An analysis similar to that performed earlier is used in the case of a microstrip with a dielectric constant $\epsilon_r = 3.78$, thickness $h = 0.127$ mm, and strip width $2d = 2.67$ mm. The results are shown in Figs. 6, 7, and 8 for different values of $C \in [0.05, 1.0]$ pF. Here, a 64° main-beam scan range is achieved at a constant frequency $f = 30$ GHz, and is accompanied by a shift of about 4 GHz in the cutoff frequency of the EH_1 mode.

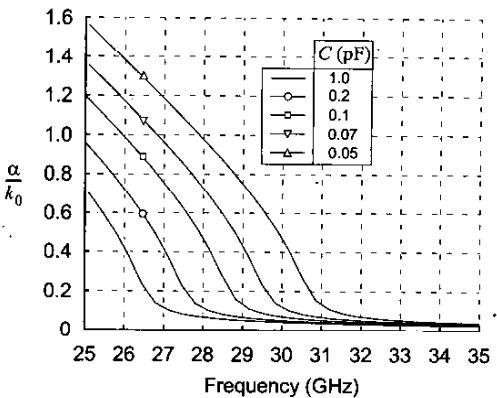


Fig. 6. The normalized leakage constant α/k_0 of the EH_1 mode in a reactively loaded microstrip with $\epsilon_r = 3.78$, $h = 0.127$ mm, $2d = 2.67$ mm, and $C \in [0.05, 1.0]$ pF.

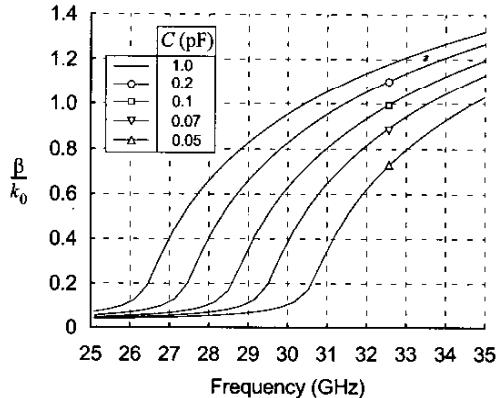


Fig. 7. The normalized phase constant β/k_0 of the EH_1 mode in a reactively loaded microstrip with $\epsilon_r = 3.78$, $h = 0.127$ mm, $2d = 2.67$ mm, and $C \in [0.05, 1.0]$ pF.

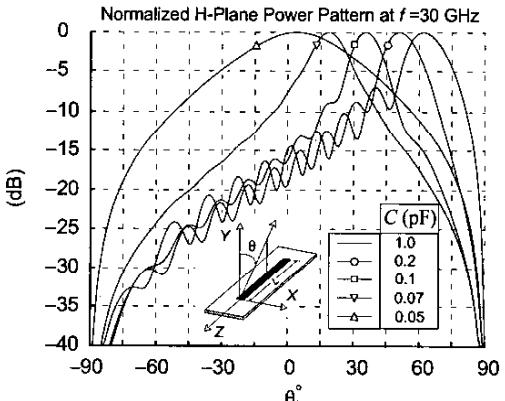


Fig. 8. The normalized H -plane power-gain patterns of the $4.9\lambda_0$ -long reactively loaded microstrip for $\epsilon_r = 3.78$, $f = 30$ GHz, and $C \in [0.05, 1.0]$ pF. The normalization factor for each of the patterns is its maximum power gain.

The reactive loading can take the form of a ferroelectric film such as BST [14]. Alternatively, a periodic array of ferroelectric strips placed in shunt across the microstrip center gap can be used, and would result in antennas with a higher radiation efficiency. Another form of loading is a periodic array of varactors (Schottky or MEMS [15]) requiring a reverse-bias voltage range that is much smaller than that used in [3,4], due to the shunt mounting of the varactors across the microstrip center gap.

III. CONCLUSIONS

In conclusion, it was found that the phase velocity along a reactively loaded microstrip operating in its first higher-order mode may be varied continuously at constant frequency by varying its surface reactance. This effect can be used to achieve fixed-frequency continuous main-beam steering.

It was also found that a change in the surface reactance is accompanied by a shift in the cutoff frequency of the first higher-order mode. This effect is similar to changing the width of the microstrip waveguide, and may be used in the design of antennas with a continuously adjustable operating frequency range.

It is interesting to note that the reactively loaded microstrip may be used as a variable-delay transmission line when operated below f_{cl} , the cutoff frequency of its first higher-order mode. On the other hand, when loaded periodically with reverse-biased Schottky varactors, and driven in large-signal mode at frequencies that are much smaller than f_{cl} , the structure may be used as a nonlinear transmission line for the generation of nonlinear waves such as electrical shock waves and solitons [16].

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